

# ORDINARY DIFFERENTIAL EQUATIONS

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**Dr. S. Sumithiradevi**  
**Assistant Professor**  
**Department of Mathematics**  
**Shrimati Indira Gandhi College**  
**Trichy.**

# Linear Equations with constant coefficients

## Differential Equation:

A differential equation is an equation which contains derivatives of one or more depended variables with respect to one or more independent variables.

## Example:

- $dy/dx = m$
- $\partial^2 y / \partial x^2 + \partial^2 y / \partial z^2 = 2xy$

## Types of differential Equations:

Differential equations are classified as follows:

- Ordinary Differential Equation
- Partial Differential Equation

## Ordinary Differential Equation:

A differential equation which involves only one independent variable.

### Example:

$$dy/dx = m$$

## Partial Differential Equation:

A differential equation which involves partial differential coefficient with respect to two or more independent variables

### Example:

$$\partial^2 y / \partial x^2 + \partial^2 y / \partial z^2 = 2xy$$

## Order and Degree of differential equation:

- The order of the highest order derivative occurred.
- The degree of the highest order derivative occurred.

### Example:

$$(d^4y/dx^4)^2 + (dy/dx)^4 = e^x$$

- Order: 4
- Degree: 2

## Linear differential equation:

A differential equation is said to be linear if the independent variable and its differential coefficients occur only in the first degree, and no product of dependent variable and/or its differential coefficient occur in the equation.

## **Non-Linear differential equation:**

A differential equation which is not linear is called non-linear differential equation.

A linear differential equation of order  $n$  with constant coefficient is an equation of the form

$$a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_n y = b(x),$$

where  $a_0 \neq 0$ ,  $a_1, a_2, \dots, a_n$  are complex constants and  $b$  is complex valued function on an interval  $I : a < x < b$ .

The operator  $L$  defined by

$$L(\phi)(x) = \phi^{(n)}(x) + a_1 \phi^{(n-1)}(x) + a_2 \phi^{(n-2)}(x) + \dots + a_n \phi(x)$$

is called as differential operator of order  $n$  with constant coefficients.

The equation  $L(y) = b(x)$  is called non-homogenous equation. If  $b(x) = 0$  for all  $x$  in  $I$  the corresponding equation  $L(y) = 0$  is called a homogenous equation.

### Initial Value Problems for Second Order Equations

We concerned with the equation  $L(y) = y'' + a_1y' + a_2y = 0$  where  $a_1$  and  $a_2$  are constants.

#### Theorem:1

Let  $a_1, a_2$  be constants and consider the equation  $L(y) = y'' + a_1y' + a_2y = 0$

1. If  $r_1, r_2$  are distinct roots of the characteristic polynomial  $p(r) = r^2 + a_1r + a_2$

Then the functions  $\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = e^{r_2 x}$  are solutions of  $L(y) = 0$ .

2. If  $r_1$  is a repeated root of the characteristic polynomial  $p(r)$ , the function

$\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = x e^{r_1 x}$  are solutions of  $L(y) = 0$ .

#### Proof:

Let  $\phi(x) = e^{rx}$  be a solutions of  $L(y) = 0$ .

$$\begin{aligned} L(e^{rx}) &= (e^{rx})'' + a_1(e^{rx})' + a_2(e^{rx}) \\ &= (r^2 + a_1r + a_2) (e^{rx}) \end{aligned}$$

$L(e^{rx}) = 0$  iff  $p(r) = r^2 + a_1r + a_2 = 0$ .

1. If  $r_1$  and  $r_2$  are distinct roots of  $p(r)$  then  $L(e^{r_1 x}) = L(e^{r_2 x}) = 0$  and  $\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = e^{r_2 x}$  are solutions of  $L(y) = 0$ .

2. If  $r_1$  is a repeated root of  $p(r)$ , then

$$P(r) = (r - r_1)^2 \text{ and } P'(r) = 2(r - r_1)$$

$$L(e^{rx}) = P(r)e^{rx} \text{ for all } r \text{ and } x.$$

$$\partial/\partial r L(e^{rx}) = \partial/\partial r [P(r)e^{rx}]$$

$$\text{which implies } L(xe^{rx}) = [P'(r) + xP(r)]e^{rx}$$

$$\text{at } r = r_1, \quad P(r_1) = P'(r_1) = 0$$

$$\text{ie) } L(xe^{r_1 x}) = 0 \quad \text{thus, showing that } xe^{r_1 x} \text{ is a solution of } L(y) = 0.$$

Thus, if  $r_1$  is a repeated root of the characteristic polynomial  $P(r)$ , then  $\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = xe^{r_1 x}$  are solutions of  $L(y) = 0$ .

## THEOREM :2

If  $\phi_1$  and  $\phi_2$  are two solution of  $L(y) = 0$  then  $C_1 \phi_1 + C_2 \phi_2$  is also a solution of  $L(y) = 0$ , where  $C_1$  and  $C_2$  are any two constants.

### PROOF:

Let  $\phi_1$  and  $\phi_2$  be two solutions of  $L(y) = 0$

$$L(\phi_1) = \phi_1'' + a_1 \phi_1' + a_2 \phi_1 = 0$$

$$L(\phi_2) = \phi_2'' + a_1 \phi_2' + a_2 \phi_2 = 0$$

Suppose  $C_1$  and  $C_2$  are any two constants then the function  $\phi$  defined by  $\phi = C_1 \phi_1 + C_2 \phi_2$  is a solution of  $L(y) = 0$

$$\begin{aligned} L(\phi) &= (C_1 \phi_1 + C_2 \phi_2)'' + a_1 (C_1 \phi_1 + C_2 \phi_2)' + a_2 (C_1 \phi_1 + C_2 \phi_2) \\ &= C_1 (\phi_1'' + a_1 \phi_1' + a_2 \phi_1) + C_2 (\phi_2'' + a_1 \phi_2' + a_2 \phi_2) \\ &= C_1 L(\phi_1) + C_2 L(\phi_2) \\ &= 0 \end{aligned}$$

The function  $\phi$  which is zero for all  $x$  is also a solution called the trivial solution of  $L(y) = 0$ .

The results of above two theorems allow us to solve all homogeneous linear second Order differential equations with constant coefficients.

### **Definition:**

An initial value problem  $L(y) = 0$  is a problem of finding a solution  $\phi$  satisfying  $\phi(x_0) = \alpha_0$  and  $\phi'(x_0) = \beta_0$  where  $x_0$  is some real number  $\alpha_0, \beta_0$  are given constants.

### **Theorem: 3 ( Existence Theorem)**

For any real  $x_0$  and constants  $\alpha, \beta$  there exists a solution  $\phi$  of the initial value problem  $L(y) = y'' + a_1y' + a_2y = 0$ ,  $y(x_0) = \alpha$ ,  $y'(x_0) = \beta$ ,  $-\infty < x < \infty$ .

### **Proof:**

By theorem 1, there exist two solutions  $\phi_1$  and  $\phi_2$  that satisfy  $L(\phi_1) = L(\phi_2) = 0$ . From theorem 2, we know that  $C_1 \phi_1 + C_2 \phi_2$  is a solution of  $L(y) = 0$ . We show that there are unique constants  $C_1, C_2$  such that  $\phi = C_1 \phi_1 + C_2 \phi_2$  satisfies  $\phi(x_0) = \alpha$  and  $\phi'(x_0) = \beta$ .

$$\phi(x_0) = C_1\phi_1(x_0) + C_2\phi_2(x_0) = \alpha$$

$$\phi'(x_0) = C_1\phi'_1(x_0) + C_2\phi'_2(x_0) = \beta$$

Above system of equations will have a unique solution  $C_1, C_2$  if the determinant

$$\begin{aligned}\Delta &= \begin{vmatrix} \phi_1(x_0) & \phi_2(x_0) \\ \phi'_1(x_0) & \phi'_2(x_0) \end{vmatrix} \\ &= \phi_1(x_0)\phi'_2(x_0) - \phi_2(x_0)\phi'_1(x_0) \neq 0\end{aligned}$$

By theorem 1, (1)  $\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = e^{r_2 x}$  are two solution of  $L(y) = 0$  for  $r_1 \neq r_2$  and

$$\begin{aligned}\Delta &= e^{r_1 x_0} r_2 e^{r_2 x_0} - e^{r_2 x_0} r_1 e^{r_1 x_0} \\ &= (r_2 - r_1) e^{(r_1 + r_2)x_0} \neq 0\end{aligned}$$

By theorem 1, (2)  $\phi_1(x) = e^{r_1 x}$  and  $\phi_2(x) = e^{r_2 x}$  are two solutions of  $L(y) = 0$  and

$$\begin{aligned}\Delta &= e^{r_1 x_0} [e^{r_1 x_0} + x_0 r_1 e^{r_1 x_0}] - x_0 e^{r_1 x_0} r_1 e^{r_1 x_0} \\ &= e^{2r_1 x_0} \neq 0\end{aligned}$$

Thus, the determinant condition is satisfied in both the cases. Therefore  $C_1, C_2$  are uniquely determined. The function  $\phi = C_1 \phi_1 + C_2 \phi_2$  is the desired solution of the initial value problem.

Thank  
you